SIEMENS

Data sheet for SINAMICS G120X

Article No. :

6SL3220-3YE16-0AF0



Figure similar

| Client order no. : |
|--------------------|
| Order no. : |
| Offer no. : |
| Remarks : |

| Rate | d data | |
|-------------------------------------|-----------------|------------------------|
| Input | | |
| Number of phases | 3 AC | |
| Line voltage | 380 480 V +10 % | % -20 % |
| Line frequency | 47 63 Hz | |
| Rated voltage | 400V IEC | 480V NEC |
| Rated current (LO) | 5.50 A | 4.60 A |
| Rated current (HO) | 3.60 A | 3.00 A |
| Output | | |
| Number of phases | 3 AC | |
| Rated voltage | 400V IEC | 480V NEC ¹⁾ |
| Rated power (LO) | 2.20 kW | 3.00 hp |
| Rated power (HO) | 1.50 kW | 2.00 hp |
| Rated current (LO) | 5.90 A | 4.80 A |
| Rated current (HO) | 4.10 A | 3.40 A |
| Rated current (IN) | 6.10 A | |
| Max. output current | 6.40 A | |
| Pulse frequency | 4 kHz | |
| Output frequency for vector control | 0 200 Hz | |
| Output frequency for V/f control | 0 550 Hz | |
| | | |

Overload capability

Low Overload (LO)

110% base load current IL for 60 s in a 300 s cycle time

High Overload (HO)

150% x base load current IH for 60 s within a 600 s cycle time

| General tech. specifications | | |
|-----------------------------------|---|--|
| Power factor λ | 0.70 0.85 | |
| Offset factor $\cos \phi$ | 0.96 | |
| Efficiency η | 0.97 | |
| Sound pressure level (1m) | 55 dB | |
| Power loss ³⁾ | 0.091 kW | |
| Filter class (integrated) | RFI suppression filter for Category C2 | |
| EMC category (with accessories) | Category C2 | |
| Safety function "Safe Torque Off" | without SIRIUS device (e.g. via S7- 1500F) | |
| Communication | | |

Communication

PROFINET, EtherNet/IP

ltem no. : Consignment no. : Project :

| Summer of digital inputsNumber6Switching level: $0 \rightarrow 1$ 11 VSwitching level: $1 \rightarrow 0$ 5 VMax. inrush current15 mAInformation of the second | Inputs / outputs | | |
|---|--------------------------------------|--|--|
| Number1Switching level: $0 \rightarrow 1$ 11 VSwitching level: $1 \rightarrow 0$ 5 VMax. inrush current15 mAFail-safe digital inputs1Digital outputs0Number as relay changeover contact2Output (resistive load)DC 30 V, 5.0 ANumber as transistor0Analog / digital inputsNumber2 (Differential input)Resolution10 bitSwitching threshold as digital input $0 \rightarrow 1$ $4 \vee$ $1 \rightarrow 0$ $1.6 \vee$ Analog outputs1 (Non-isolated output)PTC/ KTY interface1 motor temperature sensor input, sensors that can be connected PTC, KTY and | Standard digital inputs | | |
| Switching level: $1 \rightarrow 0$ 5 VMax. inrush current15 mAFail-safe digital inputsNumber1Digital outputsNumber as relay changeover contact2Output (resistive load)DC 30 V, 5.0 ANumber as transistor0Analog / digital inputs2 (Differential input)Resolution10 bitTo $1 \rightarrow 0$ 4 V $1 \rightarrow 0$ 1.6 VAnalog outputs1 (Non-isolated output)Number1 (Non-isolated output)I motor temperature sensor input, sensors that can be connected PTC, KTY and | Number | 6 | |
| Max. inrush current 15 mA Fail-safe digital inputs 1 Number 1 Digital outputs 2 Output (resistive load) DC 30 V, 5.0 A Number as relay changeover contact 2 Output (resistive load) DC 30 V, 5.0 A Number as transistor 0 Analog / digital inputs 2 (Differential input) Resolution 10 bit Switching threshold as digital input 10 bit I → 0 1.6 V Analog outputs 1 (Non-isolated output) Number 1 (Non-isolated output) | Switching level: $0 \rightarrow 1$ | 11 V | |
| Fail-safe digital inputs 1 Number 1 Digital outputs 2 Output (resistive load) DC 30 V, 5.0 A Number as relay changeover contact 2 Output (resistive load) DC 30 V, 5.0 A Number as transistor 0 Analog / digital inputs 2 (Differential input) Resolution 10 bit Switching threshold as digital input 10 bit 0 → 1 4 V 1 → 0 1.6 V Analog outputs 1 (Non-isolated output) Number 1 (Non-isolated output) | Switching level: $1 \rightarrow 0$ | 5 V | |
| Number 1 Digital outputs 1 Number as relay changeover contact 2 Output (resistive load) DC 30 V, 5.0 A Number as transistor 0 Analog / digital inputs 2 (Differential input) Resolution 10 bit Switching threshold as digital input 10 bit I → 0 1.6 V Analog outputs 1 (Non-isolated output) I → 0 1 (Non-isolated output) I motor temperature sensor input, sensors that can be connected PTC, KTY and | Max. inrush current | 15 mA | |
| Digital outputsNumber as relay changeover contact2Output (resistive load)DC 30 V, 5.0 ANumber as transistor0Analog / digital inputs2 (Differential input)Resolution10 bitSwitching threshold as digital input $4 V$ $0 \rightarrow 1$ $4 V$ $1 \rightarrow 0$ $1.6 V$ Analog outputs 1 (Non-isolated output)PTC/ KTY interface 1 motor temperature sensor input, sensors that can be connected PTC, KTY and | Fail-safe digital inputs | | |
| Number as relay changeover contact 2 Output (resistive load) DC 30 V, 5.0 A Number as transistor 0 Analog / digital inputs 2 (Differential input) Resolution 10 bit Switching threshold as digital input 10 bit 0 \rightarrow 1 4 V 1 \rightarrow 0 1.6 V Analog outputs 1 (Non-isolated output) PTC/ KTY interface 1 motor temperature sensor input, sensors that can be connected PTC, KTY and | Number | 1 | |
| Output (resistive load) DC 30 V, 5.0 A Number as transistor 0 Analog / digital inputs 2 (Differential input) Number 2 (Differential input) Resolution 10 bit Switching threshold as digital input 10 bit 0 → 1 4 V 1 → 0 1.6 V Analog outputs 1 (Non-isolated output) PTC/ KTY interface 1 motor temperature sensor input, sensors that can be connected PTC, KTY and | Digital outputs | | |
| Number as transistor 0 Analog / digital inputs 2 (Differential input) Number 2 (Differential input) Resolution 10 bit Switching threshold as digital input 10 bit 0 → 1 4 V 1 → 0 1.6 V Analog outputs 1 (Non-isolated output) PTC/ KTY interface 1 motor temperature sensor input, sensors that can be connected PTC, KTY and | Number as relay changeover contact | 2 | |
| Analog / digital inputsNumber2 (Differential input)Resolution10 bitSwitching threshold as digital input $0 \rightarrow 1$ 4 V $1 \rightarrow 0$ 1.6 VAnalog outputsNumber1 (Non-isolated output)PTC/ KTY interface1 motor temperature sensor input, sensors that can be connected PTC, KTY and | Output (resistive load) | DC 30 V, 5.0 A | |
| Number2 (Differential input)Resolution10 bitSwitching threshold as digital input $0 \rightarrow 1$ 4 V $1 \rightarrow 0$ 1.6 VAnalog outputsNumber1 (Non-isolated output)PTC/ KTY interface1 motor temperature sensor input, sensors that can be connected PTC, KTY and | Number as transistor | 0 | |
| Resolution 10 bit Switching threshold as digital input 0 → 1 0 → 1 4 V 1 → 0 1.6 V Analog outputs 1 (Non-isolated output) PTC/ KTY interface 1 motor temperature sensor input, sensors that can be connected PTC, KTY and | Analog / digital inputs | | |
| Switching threshold as digital input 0 → 1 4 V 1 → 0 1.6 V Analog outputs Instant output PTC/ KTY interface 1 (Non-isolated output) PTC/ KTY interface 1 motor temperature sensor input, sensors that can be connected PTC, KTY and | Number | 2 (Differential input) | |
| 0 → 1 4 V 1 → 0 1.6 V Analog outputs Image: Constraint of the second secon | Resolution | 10 bit | |
| 1 → 0 1.6 V Analog outputs Number 1 (Non-isolated output) PTC/ KTY interface 1 motor temperature sensor input, sensors that can be connected PTC, KTY and | Switching threshold as digital input | | |
| Analog outputs Number 1 (Non-isolated output) PTC/ KTY interface 1 motor temperature sensor input, sensors that can be connected PTC, KTY and | $0 \rightarrow 1$ | 4 V | |
| Number 1 (Non-isolated output) PTC/ KTY interface 1 motor temperature sensor input, sensors that can be connected PTC, KTY and | $1 \rightarrow 0$ | 1.6 V | |
| PTC/ KTY interface 1 motor temperature sensor input, sensors that can be connected PTC, KTY and | Analog outputs | | |
| 1 motor temperature sensor input, sensors that can be connected PTC, KTY and | Number | 1 (Non-isolated output) | |
| | PTC/ KTY interface | | |
| | | nsors that can be connected PTC, KTY and | |

| Closed-loop cor | ntrol techniques |
|---|------------------|
| V/f linear / square-law / parameterizable | Yes |
| V/f with flux current control (FCC) | Yes |
| V/f ECO linear / square-law | Yes |
| Sensorless vector control | Yes |
| Vector control, with sensor | No |
| Encoderless torque control | No |
| Torque control, with encoder | No |

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Data sheet for SINAMICS G120X

Article No. :

6SL3220-3YE16-0AF0

| Ambie | ent conditions |
|--------------------------------|--|
| Standard board coating type | Class 3C2, according to IEC 60721-3-3: 2002 |
| Cooling | Air cooling using an integrated fan |
| Cooling air requirement | 0.005 m³/s (0.177 ft³/s) |
| Installation altitude | 1,000 m (3,280.84 ft) |
| Ambient temperature | |
| Operation | -20 45 °C (-4 113 °F) |
| Transport | -40 70 °C (-40 158 °F) |
| Storage | -25 55 °C (-13 131 °F) |
| Relative humidity | |
| Max. operation | 95 % At 40 $^\circ\text{C}$ (104 $^\circ\text{F}), condensation and icing not permissible$ |
| Co | nnections |
| Signal cable | |
| Conductor cross-section | 0.15 1.50 mm² (AWG 24 AWG 16) |
| Line side | |
| Version | screw-type terminal |
| Conductor cross-section | 1.50 2.50 mm ² (AWG 16 AWG 14) |
| Motor end | |
| Version | Screw-type terminals |
| Conductor cross-section | 1.50 2.50 mm ² (AWG 16 AWG 14) |
| DC link (for braking resistor) | |
| - | |
| PE connection | On housing with M4 screw |
| | On housing with M4 screw |
| PE connection | On housing with M4 screw 150 m (492.13 ft) |

| Me | echanical data | |
|---|--|--------------------------------------|
| Degree of protection | IP20 / UL oper | n type |
| Frame size | FSA | |
| Net weight | 3.4 kg (7.50 l | b) |
| Dimensions | | |
| Width | 73 mm (2.87 | in) |
| Height | 232 mm (9.1 | 3 in) |
| Depth | 218 mm (8.5 | 8 in) |
| | Standards | |
| Compliance with standards | dards UL, cUL, CE, C-Tick (RCM), EAC, KCC SEMI F47, REACH | |
| CE marking | | 2004/108/EC, Low- tive 2006/95/EC |
| Converter lo | osses to IEC61800 | -9-2* |
| Efficiency class | IE2 | |
| Comparison with the reference converter (90% / 100%) | 33.3 % | |
| ■ 65.8 W (1.6 %) | 75.4 W (1.8 %) | 91.4 W (2.2 %) |
| 51.2 W (1.3 %) | 55.2 W (1.4 %) | ∳61.0 W (1.5 %) |
| 45.3 W (1.1 %) | 47.0 W (1.2 %) | |
| | | |

The percentage values show the losses in relation to the rated apparent power of the converter.

The diagram shows the losses for the points (as per standard IEC61800-9-2) of the relative torque generating current (I) over the relative motor stator frequency (f). The values are valid for the basic version of the converter without options/components.

*converted values

¹⁾The output current and HP ratings are valid for the voltage range 440V-480V

³⁾Typical value. More information can be found in the element group "Converter losses to IEC 61800-9-2" in this datasheet.

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Article No. :

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| | Operator panel: Intelli | igen |
|----------------------|-------------------------|------|
| Screen | |] |
| Display design | LCD color | - |
| Screen resolution | 320 x 240 Pixel | |
| | | 7 |
| | Mechanical data | |
| Degree of protection | IP55 / UL type 12 | |
| Net weight | 0.134 kg (0.30 lb) | |
| Dimensions | | |
| Width | 70.00 mm (2.76 in) | |
| Height | 106.85 mm (4.21 in) | |
| Depth | 19.65 mm (0.77 in) | |

| Ambient conditions Ambient temperature | | |
|--|---------------------------------------|--|
| | | |
| | 55 °C only with door installation kit | |
| Storage | -40 70 °C (-40 158 °F) | |
| Transport | -40 70 °C (-40 158 °F) | |
| Relative humidity at 25°C durir | ng | |
| Max. operation | 95 % | |
| | Approvals | |