SIEMENS

Data sheet for SINAMICS G120X

Article No. :

6SL3220-3YE16-0AF0



Figure similar

Client order no. :
Order no. :
Offer no. :
Remarks :

Rate	d data	
Input		
Number of phases	3 AC	
Line voltage	380 480 V +10 %	% -20 %
Line frequency	47 63 Hz	
Rated voltage	400V IEC	480V NEC
Rated current (LO)	5.50 A	4.60 A
Rated current (HO)	3.60 A	3.00 A
Output		
Number of phases	3 AC	
Rated voltage	400V IEC	480V NEC ¹⁾
Rated power (LO)	2.20 kW	3.00 hp
Rated power (HO)	1.50 kW	2.00 hp
Rated current (LO)	5.90 A	4.80 A
Rated current (HO)	4.10 A	3.40 A
Rated current (IN)	6.10 A	
Max. output current	6.40 A	
Pulse frequency	4 kHz	
Output frequency for vector control	0 200 Hz	
Output frequency for V/f control	0 550 Hz	

Overload capability

Low Overload (LO)

110% base load current IL for 60 s in a 300 s cycle time

High Overload (HO)

150% x base load current IH for 60 s within a 600 s cycle time

General tech. specifications		
Power factor λ	0.70 0.85	
Offset factor $\cos \phi$	0.96	
Efficiency η	0.97	
Sound pressure level (1m)	55 dB	
Power loss ³⁾	0.091 kW	
Filter class (integrated)	RFI suppression filter for Category C2	
EMC category (with accessories)	Category C2	
Safety function "Safe Torque Off"	without SIRIUS device (e.g. via S7- 1500F)	
Communication		

Communication

PROFINET, EtherNet/IP

ltem no. : Consignment no. : Project :

Summer of digital inputsNumber6Switching level: $0 \rightarrow 1$ 11 VSwitching level: $1 \rightarrow 0$ 5 VMax. inrush current15 mAInformation of the second	Inputs / outputs		
Number1Switching level: $0 \rightarrow 1$ 11 VSwitching level: $1 \rightarrow 0$ 5 VMax. inrush current15 mAFail-safe digital inputs1Digital outputs0Number as relay changeover contact2Output (resistive load)DC 30 V, 5.0 ANumber as transistor0Analog / digital inputsNumber2 (Differential input)Resolution10 bitSwitching threshold as digital input $0 \rightarrow 1$ $4 \vee$ $1 \rightarrow 0$ $1.6 \vee$ Analog outputs1 (Non-isolated output)PTC/ KTY interface1 motor temperature sensor input, sensors that can be connected PTC, KTY and	Standard digital inputs		
Switching level: $1 \rightarrow 0$ 5 VMax. inrush current15 mAFail-safe digital inputsNumber1Digital outputsNumber as relay changeover contact2Output (resistive load)DC 30 V, 5.0 ANumber as transistor0Analog / digital inputs2 (Differential input)Resolution10 bitTo $1 \rightarrow 0$ 4 V $1 \rightarrow 0$ 1.6 VAnalog outputs1 (Non-isolated output)Number1 (Non-isolated output)I motor temperature sensor input, sensors that can be connected PTC, KTY and	Number	6	
Max. inrush current 15 mA Fail-safe digital inputs 1 Number 1 Digital outputs 2 Output (resistive load) DC 30 V, 5.0 A Number as relay changeover contact 2 Output (resistive load) DC 30 V, 5.0 A Number as transistor 0 Analog / digital inputs 2 (Differential input) Resolution 10 bit Switching threshold as digital input 10 bit I → 0 1.6 V Analog outputs 1 (Non-isolated output) Number 1 (Non-isolated output)	Switching level: $0 \rightarrow 1$	11 V	
Fail-safe digital inputs 1 Number 1 Digital outputs 2 Output (resistive load) DC 30 V, 5.0 A Number as relay changeover contact 2 Output (resistive load) DC 30 V, 5.0 A Number as transistor 0 Analog / digital inputs 2 (Differential input) Resolution 10 bit Switching threshold as digital input 10 bit 0 → 1 4 V 1 → 0 1.6 V Analog outputs 1 (Non-isolated output) Number 1 (Non-isolated output)	Switching level: $1 \rightarrow 0$	5 V	
Number 1 Digital outputs 1 Number as relay changeover contact 2 Output (resistive load) DC 30 V, 5.0 A Number as transistor 0 Analog / digital inputs 2 (Differential input) Resolution 10 bit Switching threshold as digital input 10 bit I → 0 1.6 V Analog outputs 1 (Non-isolated output) I → 0 1 (Non-isolated output) I motor temperature sensor input, sensors that can be connected PTC, KTY and	Max. inrush current	15 mA	
Digital outputsNumber as relay changeover contact2Output (resistive load)DC 30 V, 5.0 ANumber as transistor0Analog / digital inputs2 (Differential input)Resolution10 bitSwitching threshold as digital input $4 V$ $0 \rightarrow 1$ $4 V$ $1 \rightarrow 0$ $1.6 V$ Analog outputs 1 (Non-isolated output)PTC/ KTY interface 1 motor temperature sensor input, sensors that can be connected PTC, KTY and	Fail-safe digital inputs		
Number as relay changeover contact 2 Output (resistive load) DC 30 V, 5.0 A Number as transistor 0 Analog / digital inputs 2 (Differential input) Resolution 10 bit Switching threshold as digital input 10 bit 0 \rightarrow 1 4 V 1 \rightarrow 0 1.6 V Analog outputs 1 (Non-isolated output) PTC/ KTY interface 1 motor temperature sensor input, sensors that can be connected PTC, KTY and	Number	1	
Output (resistive load) DC 30 V, 5.0 A Number as transistor 0 Analog / digital inputs 2 (Differential input) Number 2 (Differential input) Resolution 10 bit Switching threshold as digital input 10 bit 0 → 1 4 V 1 → 0 1.6 V Analog outputs 1 (Non-isolated output) PTC/ KTY interface 1 motor temperature sensor input, sensors that can be connected PTC, KTY and	Digital outputs		
Number as transistor 0 Analog / digital inputs 2 (Differential input) Number 2 (Differential input) Resolution 10 bit Switching threshold as digital input 10 bit 0 → 1 4 V 1 → 0 1.6 V Analog outputs 1 (Non-isolated output) PTC/ KTY interface 1 motor temperature sensor input, sensors that can be connected PTC, KTY and	Number as relay changeover contact	2	
Analog / digital inputsNumber2 (Differential input)Resolution10 bitSwitching threshold as digital input $0 \rightarrow 1$ 4 V $1 \rightarrow 0$ 1.6 VAnalog outputsNumber1 (Non-isolated output)PTC/ KTY interface1 motor temperature sensor input, sensors that can be connected PTC, KTY and	Output (resistive load)	DC 30 V, 5.0 A	
Number2 (Differential input)Resolution10 bitSwitching threshold as digital input $0 \rightarrow 1$ 4 V $1 \rightarrow 0$ 1.6 VAnalog outputsNumber1 (Non-isolated output)PTC/ KTY interface1 motor temperature sensor input, sensors that can be connected PTC, KTY and	Number as transistor	0	
Resolution 10 bit Switching threshold as digital input 0 → 1 0 → 1 4 V 1 → 0 1.6 V Analog outputs 1 (Non-isolated output) PTC/ KTY interface 1 motor temperature sensor input, sensors that can be connected PTC, KTY and	Analog / digital inputs		
Switching threshold as digital input 0 → 1 4 V 1 → 0 1.6 V Analog outputs Instant output PTC/ KTY interface 1 (Non-isolated output) PTC/ KTY interface 1 motor temperature sensor input, sensors that can be connected PTC, KTY and	Number	2 (Differential input)	
0 → 1 4 V 1 → 0 1.6 V Analog outputs Image: Constraint of the second secon	Resolution	10 bit	
1 → 0 1.6 V Analog outputs Number 1 (Non-isolated output) PTC/ KTY interface 1 motor temperature sensor input, sensors that can be connected PTC, KTY and	Switching threshold as digital input		
Analog outputs Number 1 (Non-isolated output) PTC/ KTY interface 1 motor temperature sensor input, sensors that can be connected PTC, KTY and	$0 \rightarrow 1$	4 V	
Number 1 (Non-isolated output) PTC/ KTY interface 1 motor temperature sensor input, sensors that can be connected PTC, KTY and	$1 \rightarrow 0$	1.6 V	
PTC/ KTY interface 1 motor temperature sensor input, sensors that can be connected PTC, KTY and	Analog outputs		
1 motor temperature sensor input, sensors that can be connected PTC, KTY and	Number	1 (Non-isolated output)	
	PTC/ KTY interface		
		nsors that can be connected PTC, KTY and	

Closed-loop cor	ntrol techniques
V/f linear / square-law / parameterizable	Yes
V/f with flux current control (FCC)	Yes
V/f ECO linear / square-law	Yes
Sensorless vector control	Yes
Vector control, with sensor	No
Encoderless torque control	No
Torque control, with encoder	No

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Ambie	ent conditions
Standard board coating type	Class 3C2, according to IEC 60721-3-3: 2002
Cooling	Air cooling using an integrated fan
Cooling air requirement	0.005 m³/s (0.177 ft³/s)
Installation altitude	1,000 m (3,280.84 ft)
Ambient temperature	
Operation	-20 45 °C (-4 113 °F)
Transport	-40 70 °C (-40 158 °F)
Storage	-25 55 °C (-13 131 °F)
Relative humidity	
Max. operation	95 % At 40 $^\circ\text{C}$ (104 $^\circ\text{F}), condensation and icing not permissible$
Co	nnections
Signal cable	
Conductor cross-section	0.15 1.50 mm² (AWG 24 AWG 16)
Line side	
Version	screw-type terminal
Conductor cross-section	1.50 2.50 mm ² (AWG 16 AWG 14)
Motor end	
Version	Screw-type terminals
Conductor cross-section	1.50 2.50 mm ² (AWG 16 AWG 14)
DC link (for braking resistor)	
-	
PE connection	On housing with M4 screw
	On housing with M4 screw
PE connection	On housing with M4 screw 150 m (492.13 ft)

Me	echanical data	
Degree of protection	IP20 / UL oper	n type
Frame size	FSA	
Net weight	3.4 kg (7.50 l	b)
Dimensions		
Width	73 mm (2.87	in)
Height	232 mm (9.1	3 in)
Depth	218 mm (8.5	8 in)
	Standards	
Compliance with standards	dards UL, cUL, CE, C-Tick (RCM), EAC, KCC SEMI F47, REACH	
CE marking		2004/108/EC, Low- tive 2006/95/EC
Converter lo	osses to IEC61800	-9-2*
Efficiency class	IE2	
Comparison with the reference converter (90% / 100%)	33.3 %	
■ 65.8 W (1.6 %)	75.4 W (1.8 %)	91.4 W (2.2 %)
51.2 W (1.3 %)	55.2 W (1.4 %)	∳61.0 W (1.5 %)
45.3 W (1.1 %)	47.0 W (1.2 %)	

The percentage values show the losses in relation to the rated apparent power of the converter.

The diagram shows the losses for the points (as per standard IEC61800-9-2) of the relative torque generating current (I) over the relative motor stator frequency (f). The values are valid for the basic version of the converter without options/components.

*converted values

¹⁾The output current and HP ratings are valid for the voltage range 440V-480V

³⁾Typical value. More information can be found in the element group "Converter losses to IEC 61800-9-2" in this datasheet.

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	Operator panel: Intelli	igen
Screen]
Display design	LCD color	-
Screen resolution	320 x 240 Pixel	
		7
	Mechanical data	
Degree of protection	IP55 / UL type 12	
Net weight	0.134 kg (0.30 lb)	
Dimensions		
Width	70.00 mm (2.76 in)	
Height	106.85 mm (4.21 in)	
Depth	19.65 mm (0.77 in)	

Ambient conditions Ambient temperature		
	55 °C only with door installation kit	
Storage	-40 70 °C (-40 158 °F)	
Transport	-40 70 °C (-40 158 °F)	
Relative humidity at 25°C durir	ng	
Max. operation	95 %	
	Approvals	